

Today

- The meaning of the “potential functions” Ψ
- Markov properties
- The Elimination Algorithm
- The Junction Tree Algorithm

Meaning of potential functions

What are the “potential functions” ? Ψ

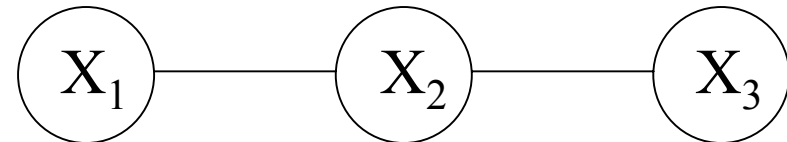
$$p(x_1x_2x_3) = p(x_1 | x_2x_3)p(x_2x_3)$$

$$p(x_1x_2x_3) = p(x_1 | x_2)p(x_2 | x_3)p(x_3)$$

$$p(x_1x_2x_3) = \frac{p(x_1x_2)}{p(x_2)} \frac{p(x_2x_3)}{p(x_3)} p(x_3)$$

$$p(x_1x_2x_3) = \frac{p(x_1x_2)p(x_2x_3)}{p(x_2)}$$

$$p(x_1x_2x_3) = \Psi_{12}(x_1x_2)\Psi_{23}(x_2x_3)$$



Where

$$\Psi_{12}(x_1x_2) = \frac{p(x_1x_2)}{p(x_2)}$$

$$\Psi_{23}(x_2x_3) = p(x_2x_3)$$

Meaning of potential functions

Think of the **potential function** $\Psi_c(x_c)$ as the “**likelihood**” of the
assignment x_c

(since they are not necessarily probabilities)

Potential functions

Example:

The potential function of a pair of neighbouring pixels can be **HIGH** if the pixels have the **same label** or **SMALL** if they have **different labels**

$$\Psi_{1,2}(x_1, x_2)$$

| | | |
|----------------------|----|----|
| $x_1 \backslash x_2$ | 0 | 1 |
| 0 | 10 | 2 |
| 1 | 2 | 10 |

$$\Psi_{1,2}(0,0) = 10$$

$$\Psi_{1,2}(0,1) = 2$$

$$\Psi_{1,2}(1,0) = 2$$

$$\Psi_{1,2}(1,1) = 10$$

Markov properties

Pairwise Markov property:

$$X_i \perp X_j \mid V \setminus \{X_i, X_j\}$$

Local Markov property:

$$X_i \perp (V \setminus \{X_i \cup bd(X_i)\}) \mid bd(X_i)$$

Global Markov property:

$$X_A \perp X_B \mid X_S$$

Elimination

Now we have smaller tables

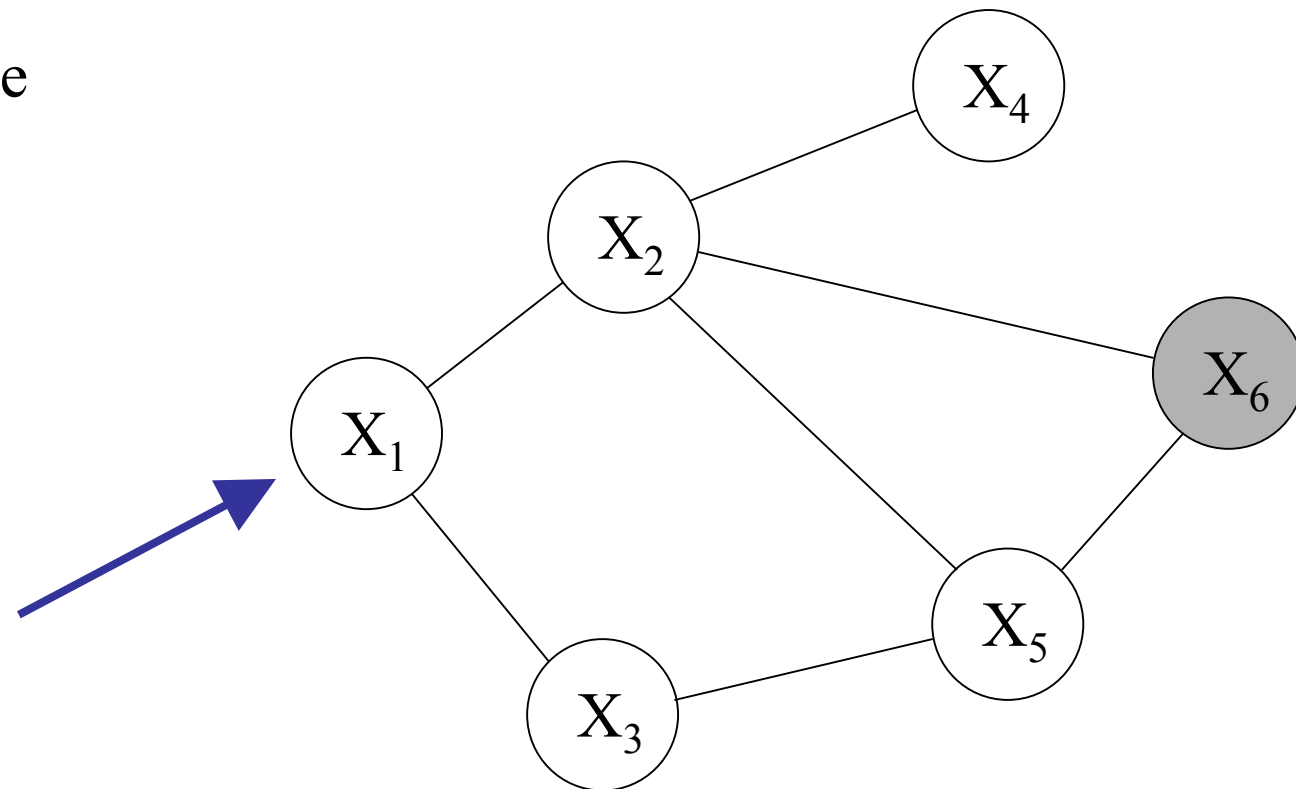
How to take advantage of the Markov structure of the graph to perform inference?

Elimination algorithm

Elimination: example

How to compute

$$p(x_1 | \bar{x}_6)$$



Elimination

$$p(x_1, \bar{x}_6) = \frac{1}{Z} \sum_{x_2} \sum_{x_3} \sum_{x_4} \sum_{x_5} \sum_{x_6} \psi(x_1, x_2) \psi(x_1, x_3) \psi(x_2, x_4) \psi(x_3, x_5) \psi(x_2, x_5, x_6) \delta(x_6, \bar{x}_6)$$

$$p(x_1, \bar{x}_6) = \frac{1}{Z} \sum_{x_2} \psi(x_1, x_2) \sum_{x_3} \psi(x_1, x_3) \sum_{x_4} \psi(x_2, x_4) \sum_{x_5} \psi(x_3, x_5) \sum_{x_6} \psi(x_2, x_5, x_6) \delta(x_6, \bar{x}_6)$$

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$$p(x_1, \bar{x}_6) = \frac{1}{Z} \sum_{x_2} \psi(x_1, x_2) \sum_{x_3} \psi(x_1, x_3) m_5(x_2, x_3) \sum_{x_4} \psi(x_2, x_4)$$

$$p(x_1, \bar{x}_6) = \frac{1}{Z} \sum_{x_2} \psi(x_1, x_2) m_4(x_2) \sum_{x_3} \psi(x_1, x_3) m_5(x_2, x_3)$$

$$p(x_1, \bar{x}_6) = \frac{1}{Z} \sum_{x_2} \psi(x_1, x_2) m_4(x_2) m_3(x_1, x_2)$$

$$p(x_1, \bar{x}_6) = \frac{1}{Z} m_2(x_1)$$

Elimination

$$p(\bar{x}_6) = \frac{1}{Z} \sum_{x_1} m_2(x_1)$$

$$p(x_1, \bar{x}_6) = \frac{1}{Z} m_2(x_1)$$

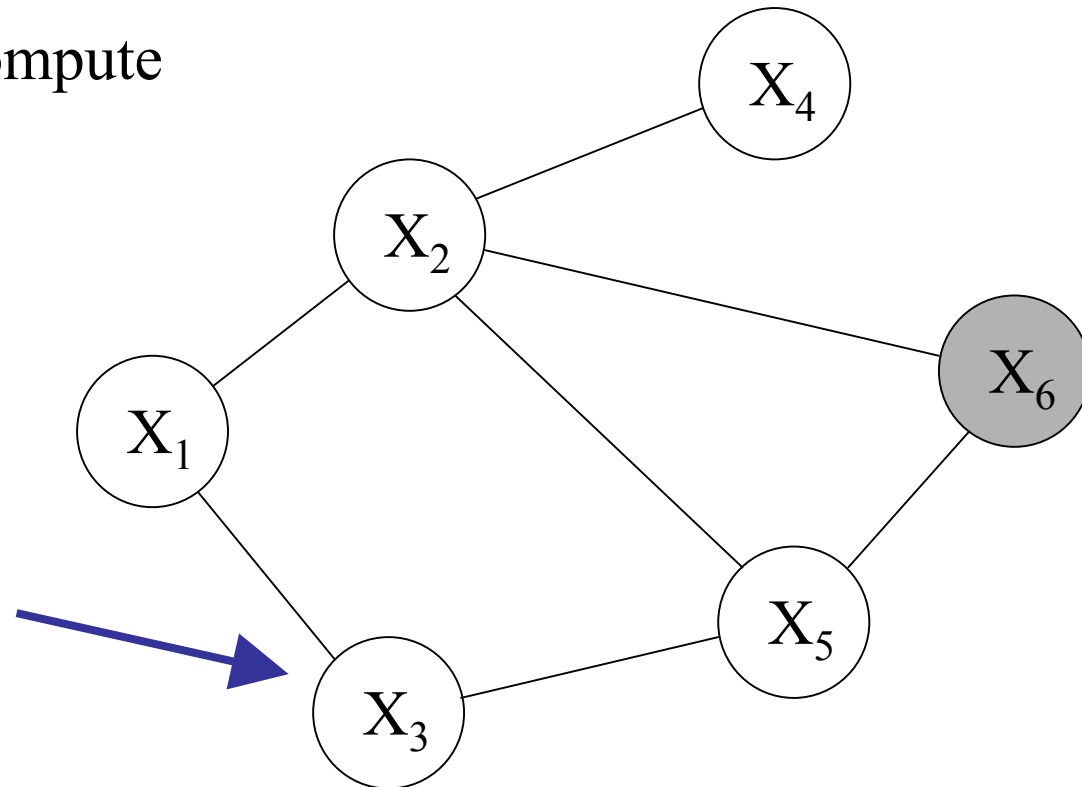


$$p(x_1 | \bar{x}_6) = \frac{m_2(x_1)}{\sum_{x_1} m_2(x_1)}$$

Elimination: example

What if now we want to compute

$$p(x_3 | \bar{x}_6)$$



Elimination: example

$$p(x_3, \bar{x}_6) = \frac{1}{Z} \sum_{x_1} \sum_{x_2} \sum_{x_4} \sum_{x_5} \sum_{x_6} \psi(x_1, x_2) \psi(x_1, x_3) \psi(x_2, x_4) \psi(x_3, x_5) \psi(x_2, x_5, x_6) \delta(x_6, \bar{x}_6)$$

$$p(x_3, \bar{x}_6) = \frac{1}{Z} \sum_{x_1} \psi(x_1, x_3) \sum_{x_2} \psi(x_1, x_2) \sum_{x_4} \psi(x_2, x_4) \sum_{x_5} \psi(x_3, x_5) \sum_{x_6} \psi(x_2, x_5, x_6) \delta(x_6, \bar{x}_6)$$

$$p(x_3, \bar{x}_6) = \frac{1}{Z} \sum_{x_1} \psi(x_1, x_3) \sum_{x_2} \psi(x_1, x_2) \sum_{x_4} \psi(x_2, x_4) \sum_{x_5} \psi(x_3, x_5) m_6(x_2, x_5)$$

$$p(x_3, \bar{x}_6) = \frac{1}{Z} \sum_{x_1} \psi(x_1, x_3) \sum_{x_2} \psi(x_1, x_2) m_5(x_2, x_3) \sum_{x_4} \psi(x_2, x_4)$$

$$p(x_3, \bar{x}_6) = \frac{1}{Z} \sum_{x_1} \psi(x_1, x_3) \sum_{x_2} \psi(x_1, x_2) m_4(x_2) m_5(x_2, x_3)$$

$$p(x_3, \bar{x}_6) = \frac{1}{Z} \sum_{x_1} m_2(x_1, x_3)$$

$$p(x_3, \bar{x}_6) = \frac{1}{Z} m_1(x_3)$$

Elimination: example

Repeated Computations!!

$$p(x_1 | \bar{x}_6)$$

$$p(x_3 | \bar{x}_6)$$

| | |
|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| $p(x_3, \bar{x}_6) = \frac{1}{Z} \sum_{x_1} \sum_{x_2} \sum_{x_4} \sum_{x_5} \sum_{x_6} \psi(x_1, x_2) \psi(x_1, x_3) \psi(x_2, x_4) \psi(x_3, x_5) \psi(x_2, x_5, x_6) \delta(x_6, \bar{x}_6)$ | $p(x_1, \bar{x}_6) = \frac{1}{Z} \sum_{x_2} \sum_{x_3} \sum_{x_4} \sum_{x_5} \sum_{x_6} \psi(x_1, x_2) \psi(x_1, x_3) \psi(x_2, x_4) \psi(x_3, x_5) \psi(x_2, x_5, x_6) \delta(x_6, \bar{x}_6)$ |
| $p(x_3, \bar{x}_6) = \frac{1}{Z} \sum_{x_1} \psi(x_1, x_3) \sum_{x_2} \psi(x_1, x_2) \sum_{x_4} \psi(x_2, x_4) \sum_{x_5} \psi(x_3, x_5) \sum_{x_6} \psi(x_2, x_5, x_6) \delta(x_6, \bar{x}_6)$ | $p(x_1, \bar{x}_6) = \frac{1}{Z} \sum_{x_2} \psi(x_1, x_2) \sum_{x_3} \psi(x_1, x_3) \sum_{x_4} \psi(x_2, x_4) \sum_{x_5} \psi(x_3, x_5) \sum_{x_6} \psi(x_2, x_5, x_6) \delta(x_6, \bar{x}_6)$ |
| $p(x_3, \bar{x}_6) = \frac{1}{Z} \sum_{x_1} \psi(x_1, x_3) \sum_{x_2} \psi(x_1, x_2) \sum_{x_4} \psi(x_2, x_4) \sum_{x_5} \psi(x_3, x_5) m_6(x_2, x_5)$ | $p(x_1, \bar{x}_6) = \frac{1}{Z} \sum_{x_2} \psi(x_1, x_2) \sum_{x_3} \psi(x_1, x_3) \sum_{x_4} \psi(x_2, x_4) \sum_{x_5} \psi(x_3, x_5) m_6(x_2, x_5)$ |
| $p(x_3, \bar{x}_6) = \frac{1}{Z} \sum_{x_1} \psi(x_1, x_3) \sum_{x_2} \psi(x_1, x_2) m_5(x_2, x_3) \sum_{x_4} \psi(x_2, x_4)$ | $p(x_1, \bar{x}_6) = \frac{1}{Z} \sum_{x_2} \psi(x_1, x_2) \sum_{x_3} \psi(x_1, x_3) m_5(x_2, x_3) \sum_{x_4} \psi(x_2, x_4)$ |
| $p(x_3, \bar{x}_6) = \frac{1}{Z} \sum_{x_1} \psi(x_1, x_3) \sum_{x_2} \psi(x_1, x_2) m_4(x_2) m_5(x_2, x_3)$ | $p(x_1, \bar{x}_6) = \frac{1}{Z} \sum_{x_2} \psi(x_1, x_2) m_4(x_2) \sum_{x_3} \psi(x_1, x_3) m_5(x_2, x_3)$ |
| $p(x_3, \bar{x}_6) = \frac{1}{Z} \sum_{x_1} m_2(x_1, x_3)$ | $p(x_1, \bar{x}_6) = \frac{1}{Z} \sum_{x_2} \psi(x_1, x_2) m_4(x_2) m_3(x_1, x_2)$ |
| $p(x_3, \bar{x}_6) = \frac{1}{Z} m_1(x_3)$ | $p(x_1, \bar{x}_6) = \frac{1}{Z} m_2(x_1)$ |

How to avoid that?

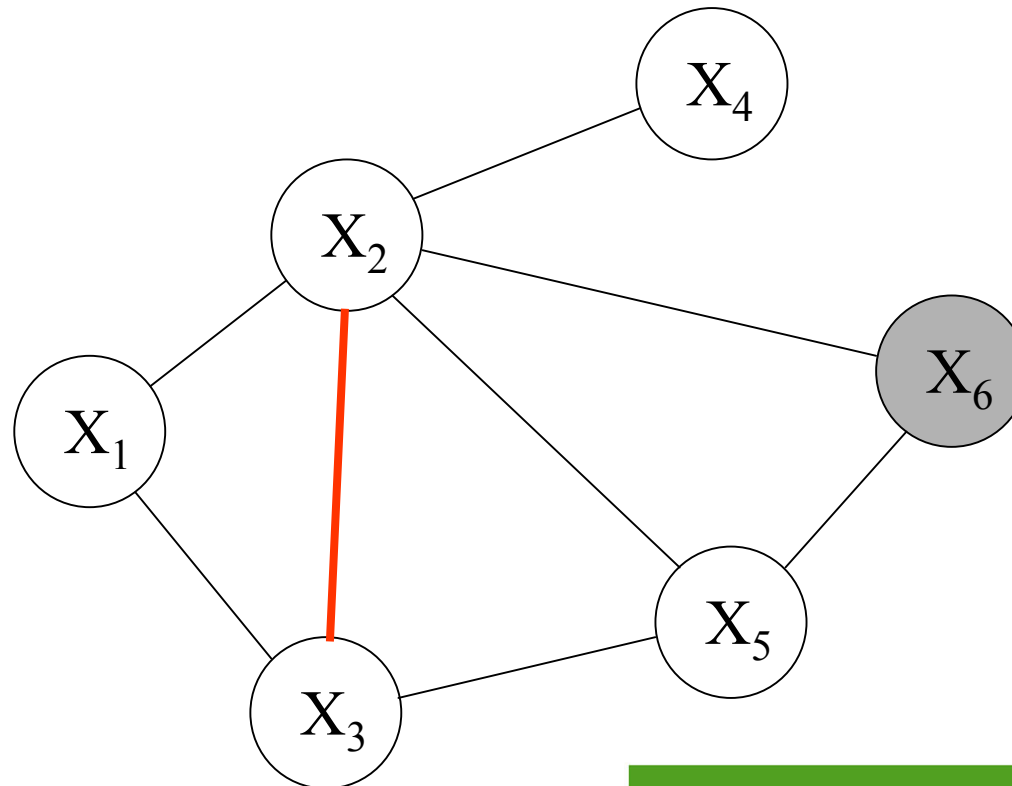
The Junction Tree Algorithm

The **Junction Tree algorithm** provides the definitive answer on how to perform exact inference in Graphical Models

It does not repeat computations

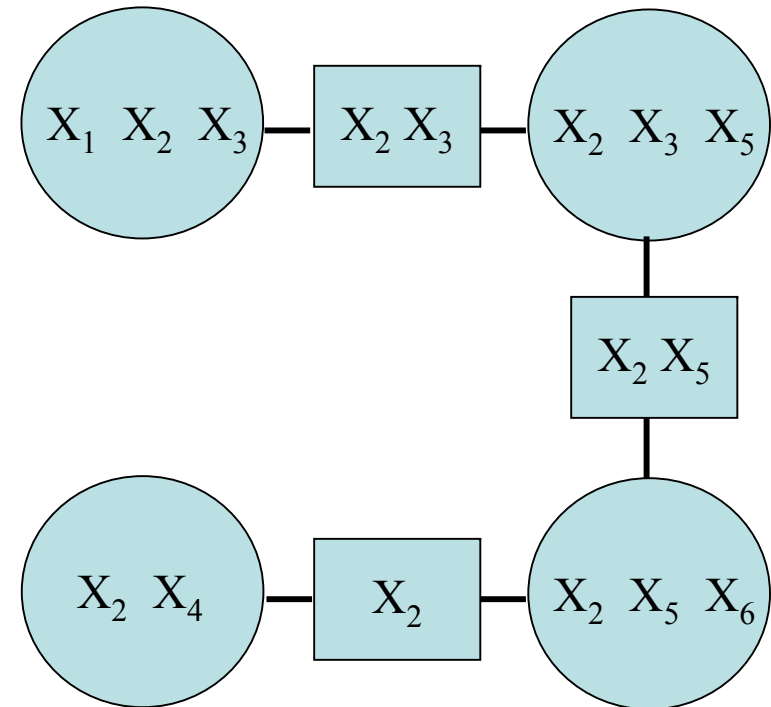
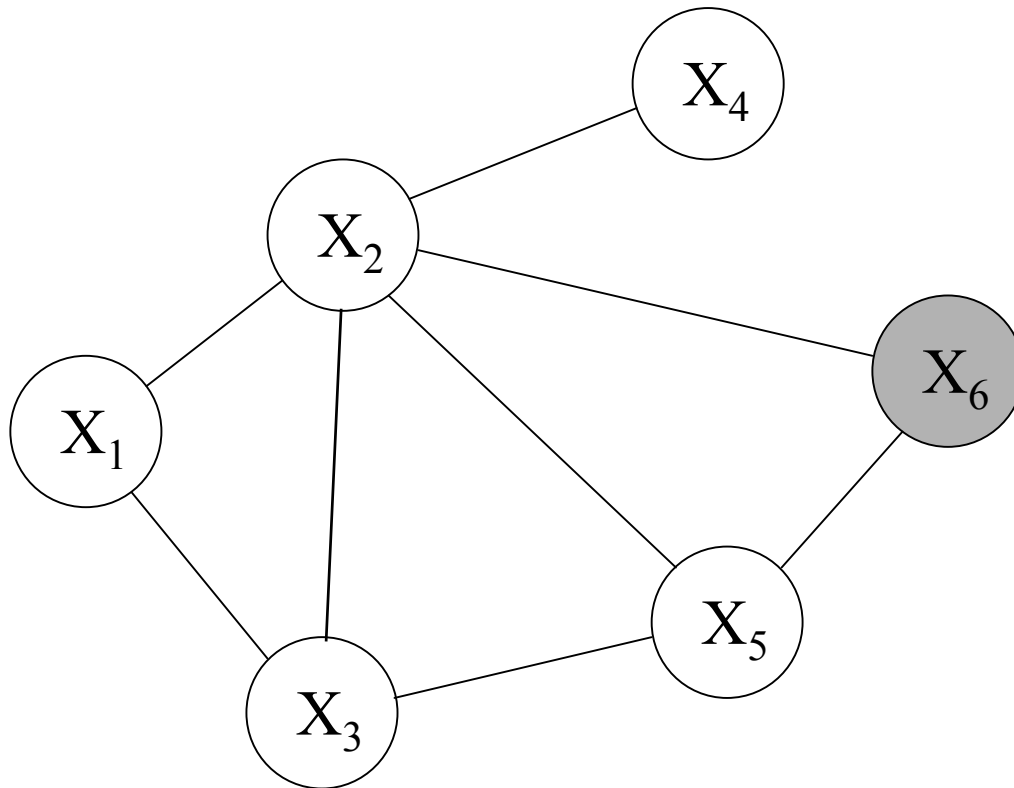
The Junction Tree Algorithm

(1) *Triangulate* the graph (if it's not triangulated)



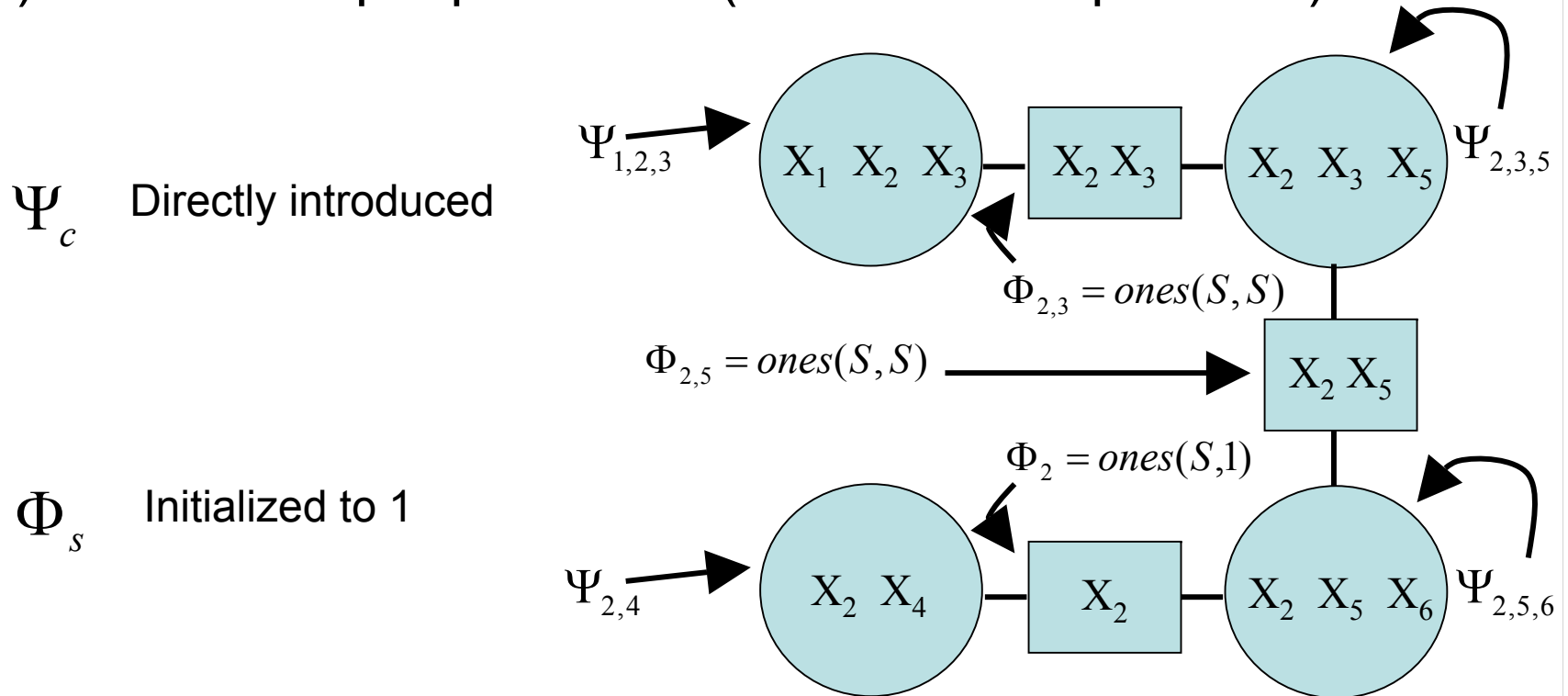
The Junction Tree Algorithm

(2) Create a Junction Tree



The Junction Tree Algorithm

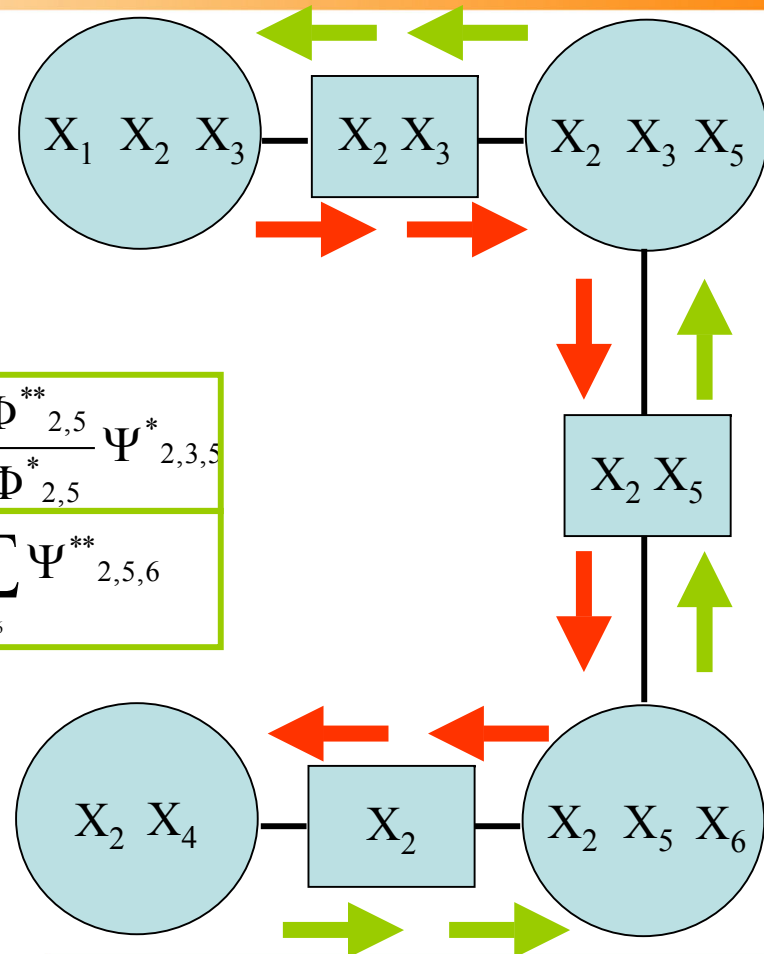
(3) Initialize clique potentials (nodes and separators)



The Junction Tree Algorithm

(4) Message passing

| | |
|-------------------------------------------------------------------------|---------------------------------------------------------------------------|
| $\Psi^{**}_{1,2,3} = \frac{\Phi^{**}_{2,3}}{\Phi^*_{2,3}} \Psi_{1,2,3}$ | $\Phi^{**}_{2,3} = \sum_{x_5} \Psi^{**}_{2,3,5}$ |
| $\Phi^*_{2,3} = \sum_{x_1} \Psi_{1,2,3}$ | $\Psi^*_{2,3,5} = \frac{\Phi^*_{2,3}}{\Phi_{2,3}} \Psi_{2,3,5}$ |
| | $\Phi^*_{2,5} = \sum_{x_3} \Psi^*_{2,3,5}$ |
| | $\Psi^{**}_{2,3,5} = \frac{\Phi^{**}_{2,5}}{\Phi^*_{2,5}} \Psi^*_{2,3,5}$ |
| | $\Psi^*_{2,5,6} = \frac{\Phi^*_{2,5}}{\Phi_{2,5}} \Psi_{2,5,6}$ |
| | $\Phi^{**}_{2,5} = \sum_{x_6} \Psi^{**}_{2,5,6}$ |
| $\Psi^*_{2,4} = \frac{\Phi^*_2}{\Phi_2} \Psi_{2,4}$ | $\Phi^*_2 = \sum_{x_5, x_6} \Psi^*_{2,5,6}$ |
| $\Phi^{**}_2 = \sum_{x_4} \Psi^*_{2,4}$ | $\Psi^*_{2,5,6} = \frac{\Phi^{**}_2}{\Phi^*_2} \Psi_{2,5,6}$ |



The Junction Tree Algorithm

Once the algorithm has finished:

potential in each clique node is equal to the marginal in that node

Marginals for singletons can then be computed by brute force